

$$d := 50 \cdot 10^{-3}$$

$$\tau_1 := 250 \cdot 10^{-3}$$

$$t_1 := 2$$

$$t_2 := 4$$

$$t_3 := 6$$

$$t_4 := 8$$

$$t_5 := 10$$

$$A_{\text{sez}} := \frac{\pi \cdot d^2}{4}$$

$$\tau_2 := 800 \cdot 10^{-3}$$

$$i := 1$$

$$j := 3$$

$$p_{\text{max}} := 200000$$

$$F_{\text{max}} := p_{\text{max}} \cdot A_{\text{sez}}$$

#### ▼ Pressione e forza in funzione del tempo

$$p_A(t) := \left[ p_{\text{max}} \cdot \left( 1 - e^{\frac{-t}{\tau_1}} \right) \right]$$

$$P_{\text{high}} := p_A(t_1)$$

$$p_B(t) := \left( P_{\text{high}} \cdot e^{\frac{-t}{\tau_2}} \right)$$

$$P_{\text{low}} := p_B(t_3 - t_2)$$

$$p(t) := \begin{cases} p_A(t) & \text{if } 0 \leq t \leq t_1 \\ P_{\text{high}} & \text{if } t_1 \leq t \leq t_2 \\ p_B(t - t_2) & \text{if } t_2 \leq t \leq t_3 \\ P_{\text{low}} & \text{if } t_3 \leq t \leq t_4 \\ \frac{-P_{\text{low}}}{t_5 - t_4} \cdot (t - t_5) & \text{if } t_4 \leq t \leq t_5 \\ 0 & \text{otherwise} \end{cases}$$

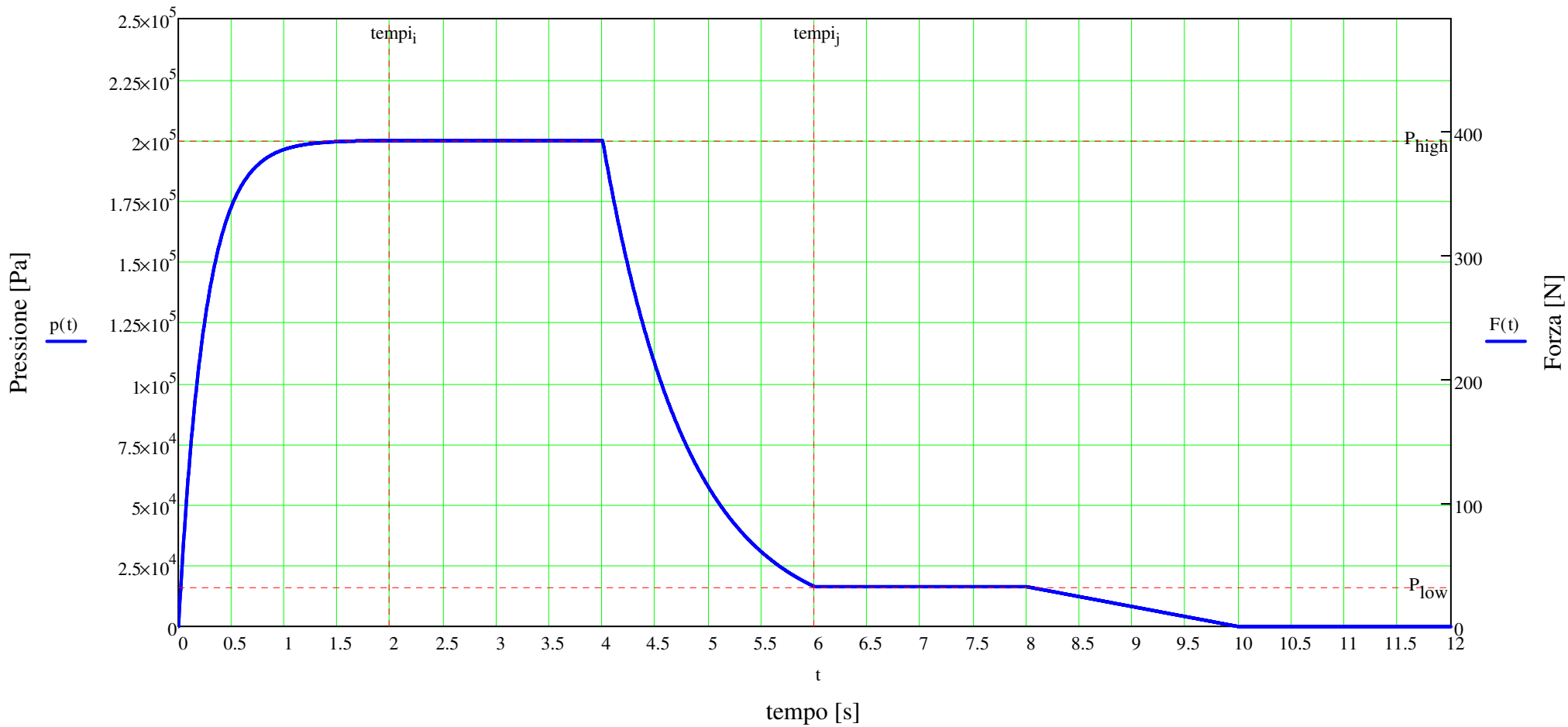
$$F(t) := A_{\text{sez}} \cdot p(t)$$

tempi :=  $\begin{pmatrix} t_1 \\ t_2 \\ t_3 \\ t_4 \\ t_5 \end{pmatrix}$

▣ Pressione e forza in funzione del tempo

$T_{\max} := 12$

$t := 0, 0.005.. T_{\max}$



## Integrazione per via numerica

ORIGIN = 1

$$M_{\text{eq}} := 30 \quad K_{\text{eq}} := 5000 \quad C_{\text{eq}} := 100$$

$$\omega := \sqrt{\frac{K_{\text{eq}}}{M_{\text{eq}}}} = 12.91 \quad f := \frac{\omega}{2 \cdot \pi} = 2.055 \quad T := \frac{1}{f} = 0.487$$

$$\xi := \frac{C_{\text{eq}}}{2 \cdot M_{\text{eq}} \cdot \omega} = 12.91\%$$

$$\Delta t_{\text{cons}} := \frac{1}{20} \cdot T = 0.024 \quad \Delta t := 0.005$$

$$x_0 := 0 \quad v_0 := 0$$

$$u := \begin{pmatrix} x_0 \\ v_0 \end{pmatrix}$$

$$\text{accel}(x, x_p, t) := \frac{1}{M_{\text{eq}}} \cdot (F(t) - K_{\text{eq}} \cdot x - C_{\text{eq}} \cdot x_p)$$

$$\text{EQMOTO}(t, u) := \begin{pmatrix} u_2 \\ \text{accel}(u_1, u_2, t) \end{pmatrix}$$

$$N_{\text{step}} := \text{ceil}\left(\frac{T_{\text{max}}}{\Delta t}\right)$$

TABELLA := rkfixed(u, 0, T<sub>max</sub>, N<sub>step</sub>, EQMOTO)

tempo := TABELLA<sup><1></sup>

SPO := TABELLA<sup><2></sup>

VEL := TABELLA<sup><3></sup>

ACC :=  $\xrightarrow{\hspace{1.5cm}}$  accel(SPO, VEL, tempo)

